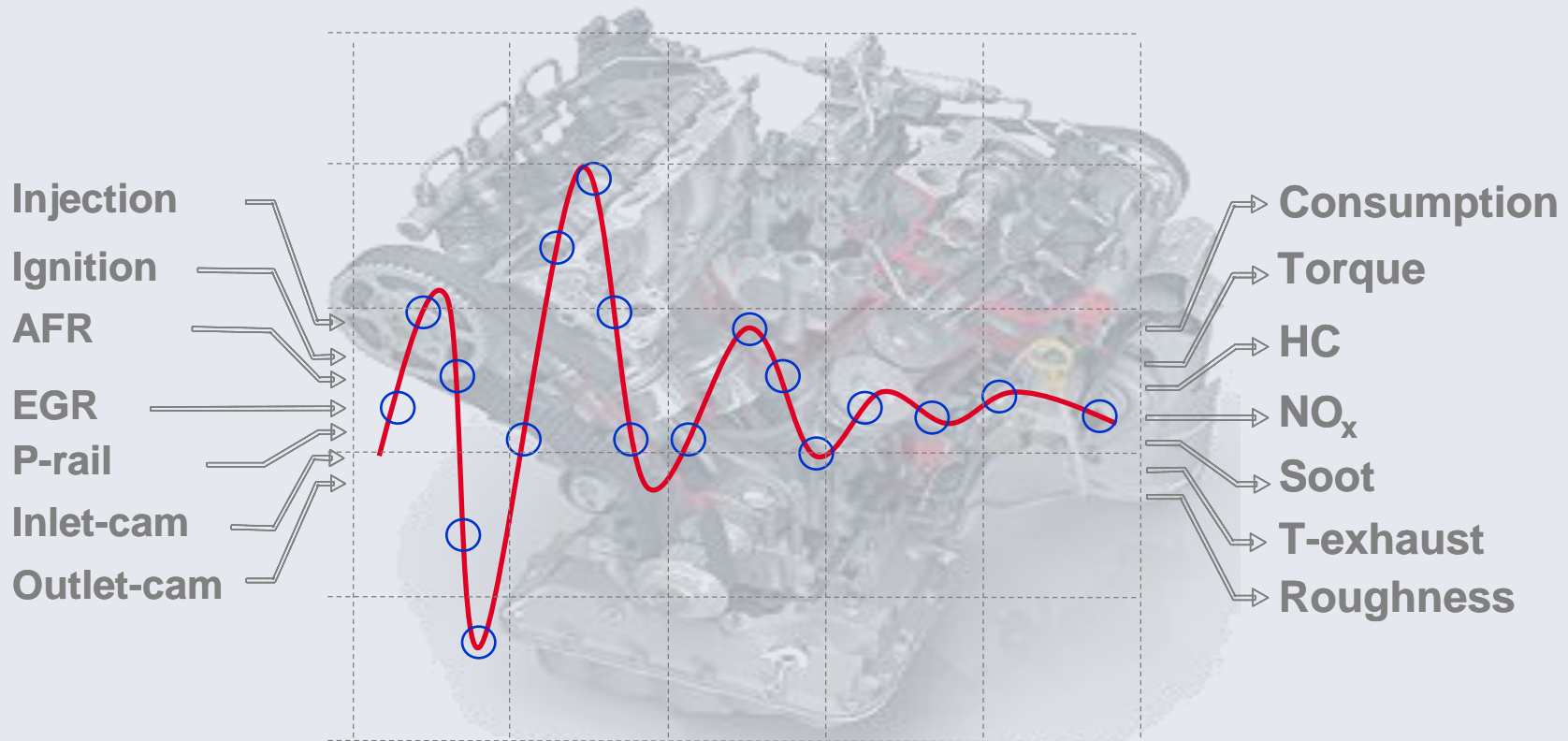


Statistical Modeling and Optimization Approaches for Development of Fuel-Efficient Vehicles



$$y(\vec{x}) = \sum_{i=1}^N C_i \cdot e^{-\frac{1}{2} \sum_{l=1}^D \frac{(X_{il} - x_l)^2}{r_l^2}}$$

Sameera C Damle
Manager – Technical Sales, Support & marketing
E-mail: sameera.damle@etas.com

- **About ETAS**
- **Challenges of today's ECU Calibration & Engine Development**
- **Model based Calibration**
- **Case Study**

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Leading Provider of Solutions and Services for Embedded Systems

- ETAS with over 850 associates is part of the Bosch Group
- Present in 13 countries with 23 offices
- ETAS subsidiary ESCRYPYPT is a specialist for embedded systems security

Numbers
apply for
ETAS and
ESCRYPYPT

ETAS Customers and Domains

Trusted by OEMs, tier one and ECU suppliers, as well as engineering service providers:

Commercial Vehicles

Automotive **Heavy Duty Engines**

Railway **Powertrain**

Construction Machines

Consumer Electronics

Off-Highway

ESCRYPYPT Customers and Domains

The ESCRYPYPT customer base includes:

Automotive

Mobile Machines & Transportation

Energy

Consumer Electronics **Mobile Devices**

Industrial Automation

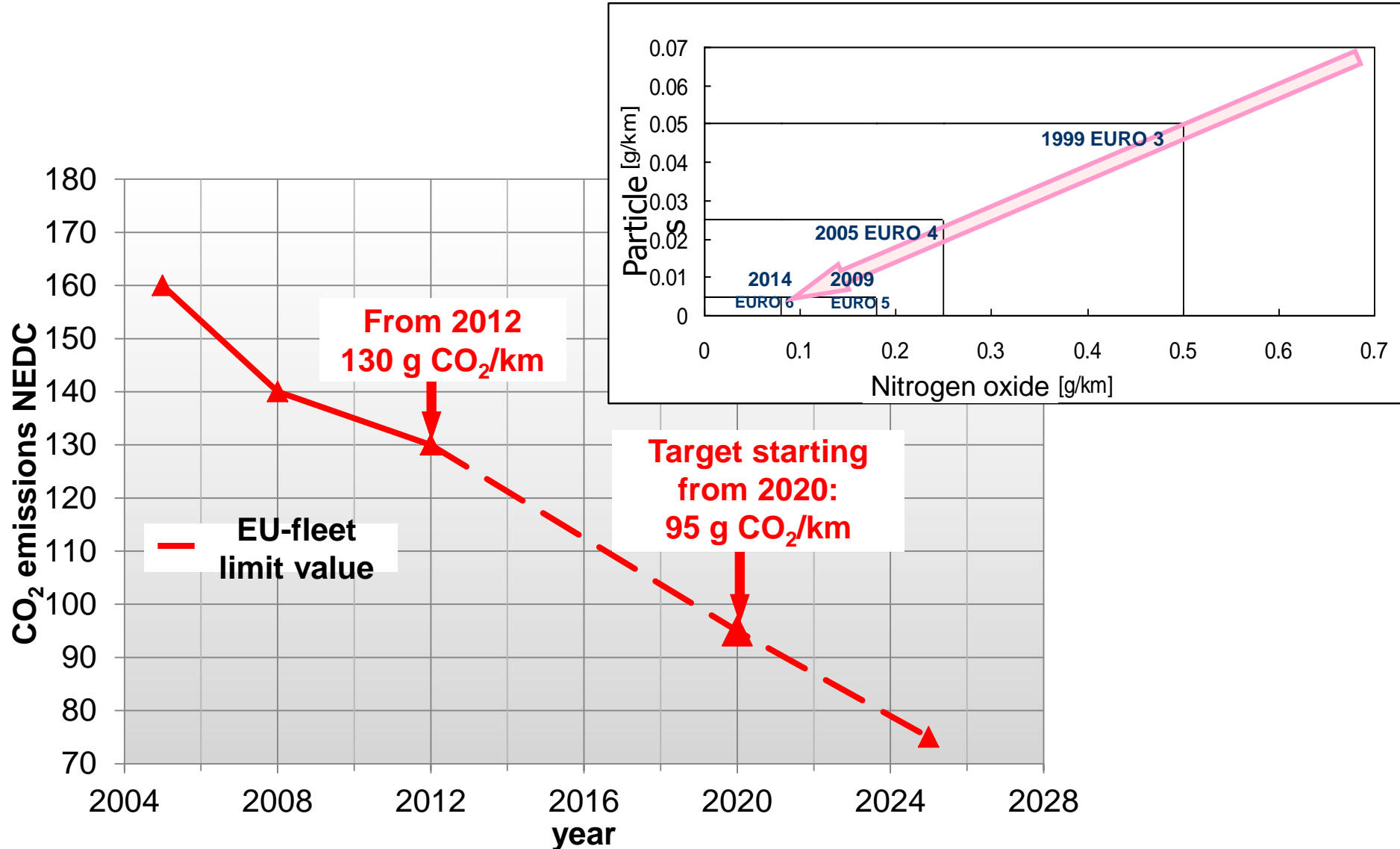
Financial & Government Logistics

Health Care

Software Engineering	Test and Validation	Measurement, Calibration, Diagnostics	Embedded Security <small>escrypt Embedded Security by ETAS</small>	Real Time Applications
ETAS Products				
Consulting and Engineering Services				
Virtualization Technology				
				

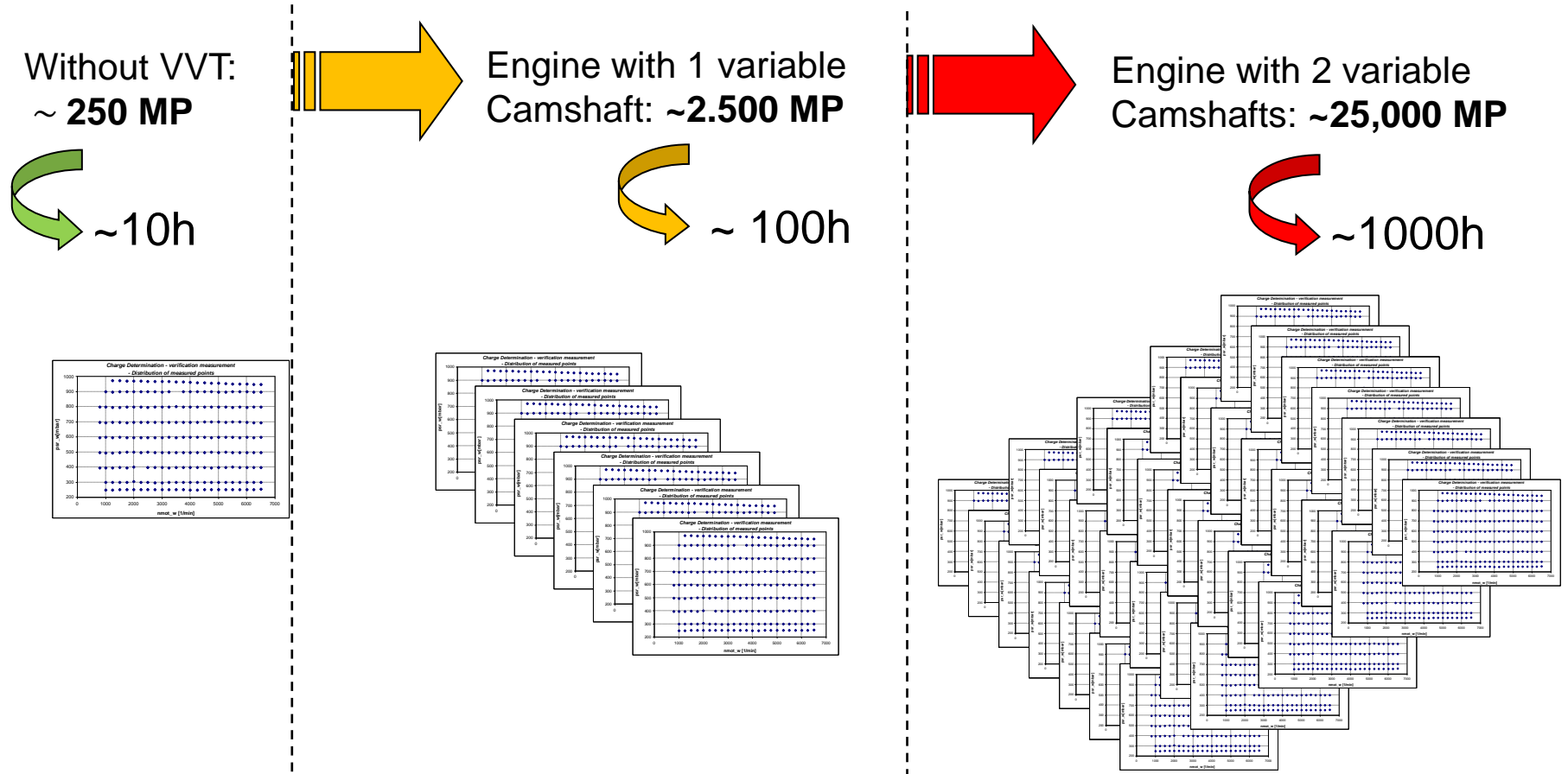
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Stringent Regulations



Classical calibration procedure: Full factorial variation of all combinations

⇒ Exponential increase with variable valve timing (VVT)



Conflicting targets

Example: Modern Gasoline Engine

Operating Range:

- Speed
- Load

Engine Parameter:

- Injection Timing
- Ignition Timing
- Fuel Pressure
- Exhaust Gas Recirculation
- Exhaust Camshaft
- Intake Camshaft
- Swirl Valve

Complex Interactions

Replacing the engine by a mathematical model:

$$y(\vec{x}) = \sum_{i=1}^N C_i \cdot e^{-\frac{1}{2} \sum_{l=1}^D \frac{(X_{il} - x_l)^2}{r_l^2}}$$

Conflicting Targets

Targets:

- Consumption/CO₂
- Emissions:
 - Soot / Particle
 - NO_x
 - HC
- Stability (CoV)
- Noise
- Exhaust-Temperature
- ...

Classical Procedure:

⇒ Full variation of all input parameters result in exponential **increase of measurement effort!**

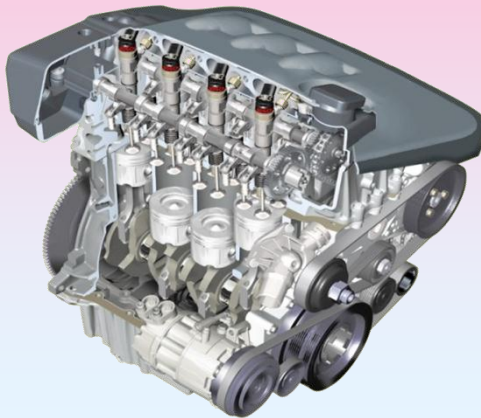
Virtual Calibration with ASCMO:

⇒ Creation of an engine model based on few specific measurements

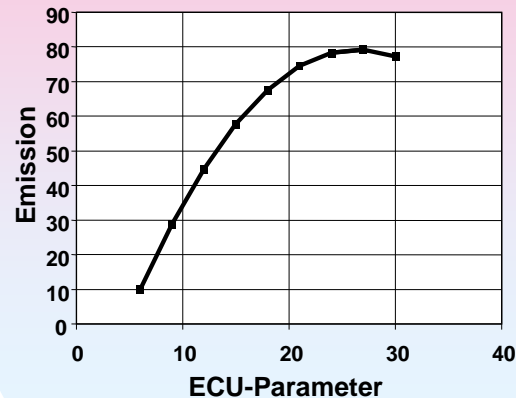
⇒ Optimization of the calibration parameter based on the model (manual or with optimizers)

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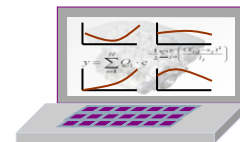
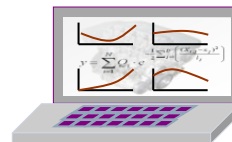
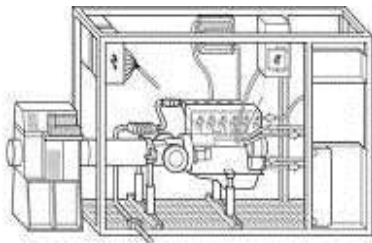
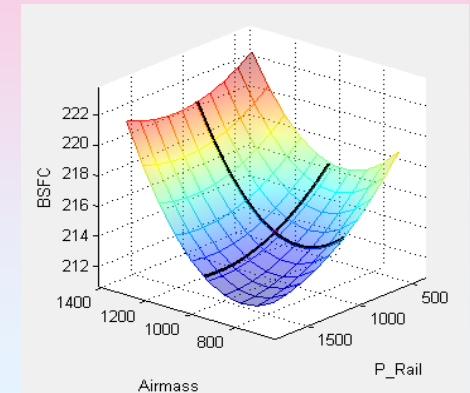
**Measuring at
the Real Engine**

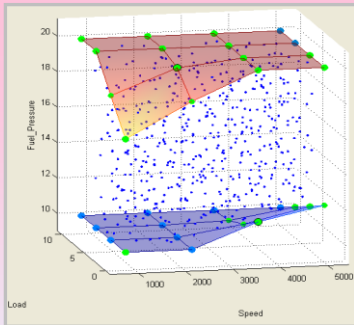


**Calculation of
an Engine Model**



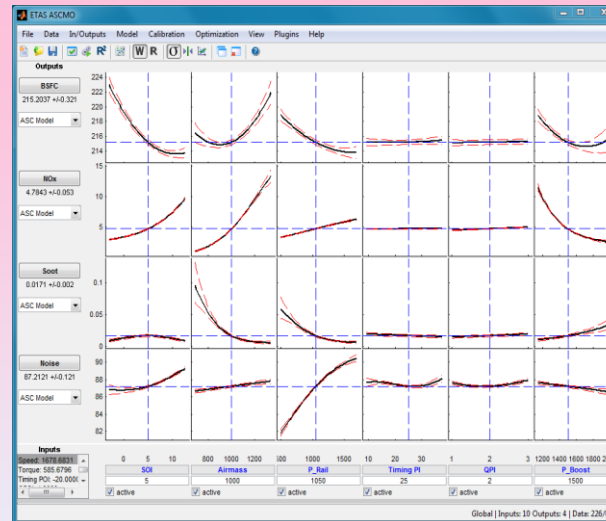
**Calibrate at the
Virtual Engine**





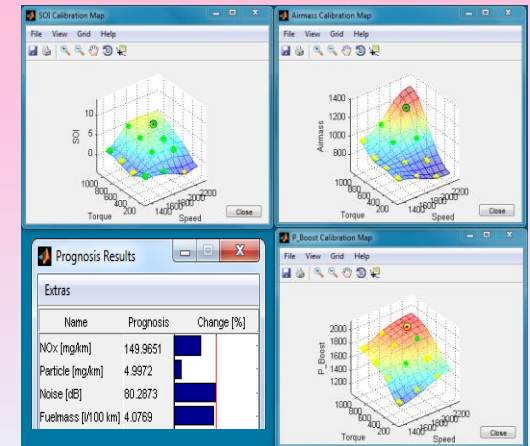
Test planning

- Robust
- Scalable
- Easy to use



Modeling

- Highest possible accuracy
- Automated model calculation
- No specific mathematical expertise necessary



Map optimization

- Global: for whole driving cycles
- Considering map-smoothness and gradients

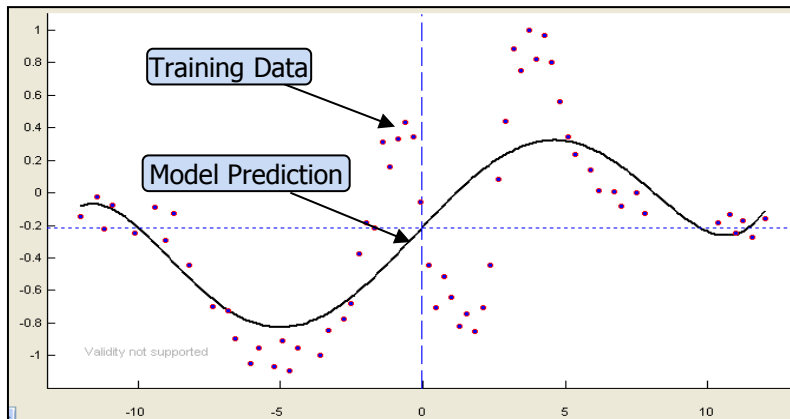
Polynomials or Neuronal Nets

Principle:

- Search in a given class of functions (polynomial, neuronal net, ...)
- Fit the model parameter by experts and validation measurements

Disadvantages:

- Limited flexibility & danger of over-fitting
- High expertise and assumptions necessary



Modeling a complex 1-D signal with classical DoE-Models („Advanced Polynomials“)

Statistical machine learning methods

Principle:

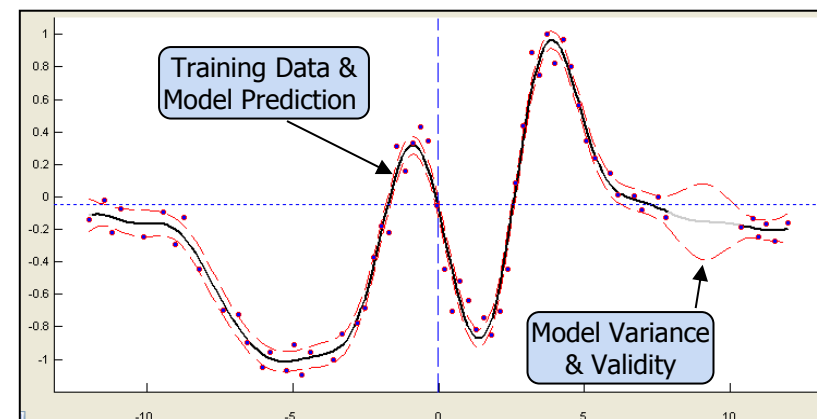
Search in a complete function space:

$$y(\vec{x}) = \sum_{i=1}^N C_i \cdot e^{-\frac{1}{2} \sum_{l=1}^D \frac{(x_l - x_{il})^2}{r_l^2}}$$

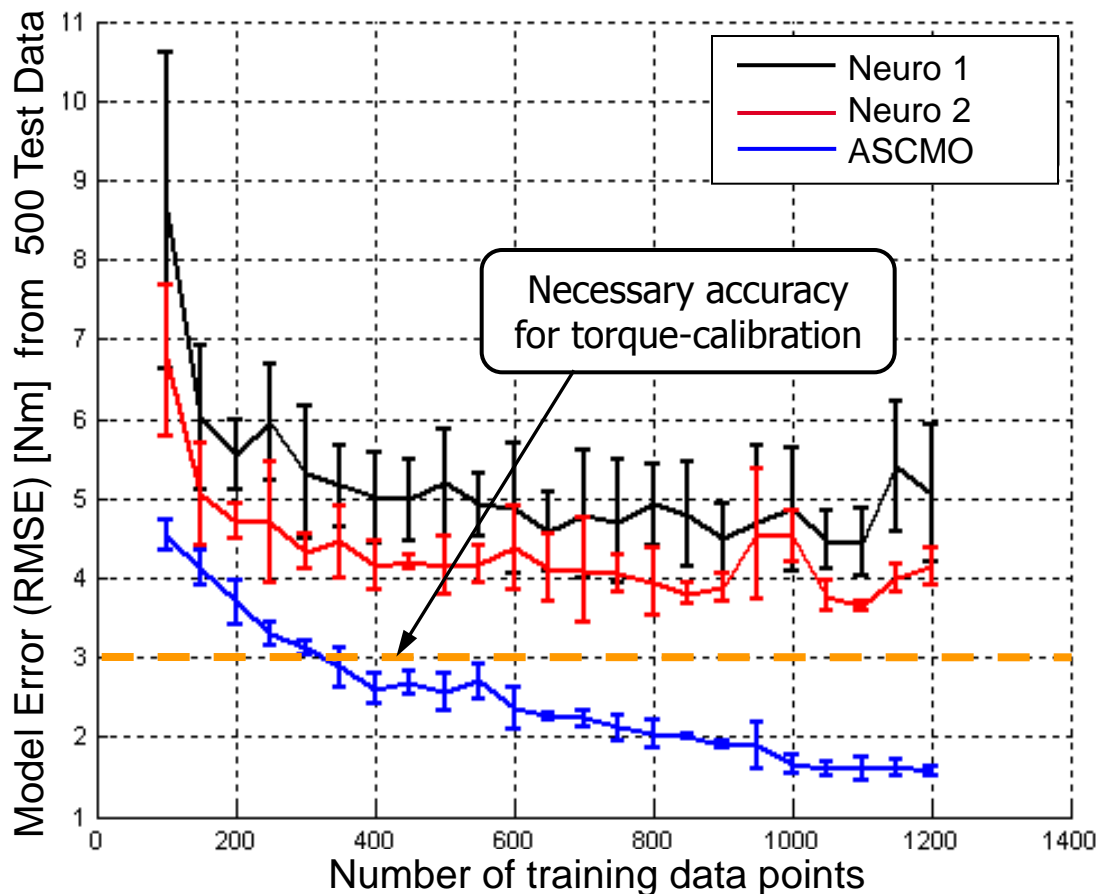
- Automatic determination of the most likely function

Advantages:

- High flexibility without assumptions or expertise
- Gives local confidence interval (model variance)
- Robust against outliers



Modeling a complex 1-D signal with new statistical machine learning methods



Benchmark:

Comparison of two different neuronal nets from commercial tools against ASCMO

Example:

Torque-modelling for a gasoline engine with variable in- & outlet-cam in the whole operating range (speed/load)

6 Parameter:

speed, load, 2 cams, AFR and ignition

Shown:

Evolution of model-error depending on number of training data:

Neural Net: **black** + **red**

ASCMO-approach: **blue**

⇒ Neural Net: insufficient accuracy even with > 1000 training data points

⇒ ASCMO: sufficient accuracy reached with 300 training data points

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Parameters:

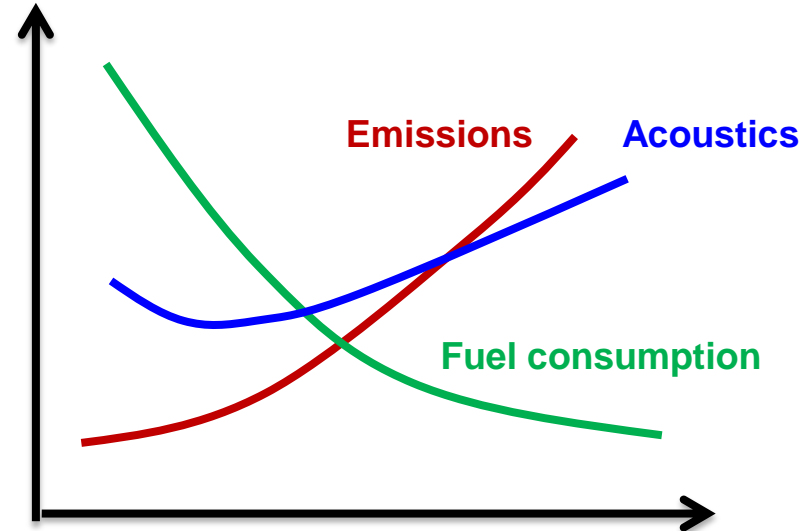
Engine speed
Injection quantity
Start of injection
Charge pressure
Air mass
Rail pressure
Swirl flap
Variable valve drive
Low pressure EGR
Exhaust gas damper
Quantity and position:
- Pre-injections
- Post-injections

**Target variables:**

Fuel consumption
Exhaust gas emissions
Response behaviour
Noise emissions
Power characteristics

Boundary conditions:

Component protection
Legal specifications

**Optimization of multiple criteria
trade-off**

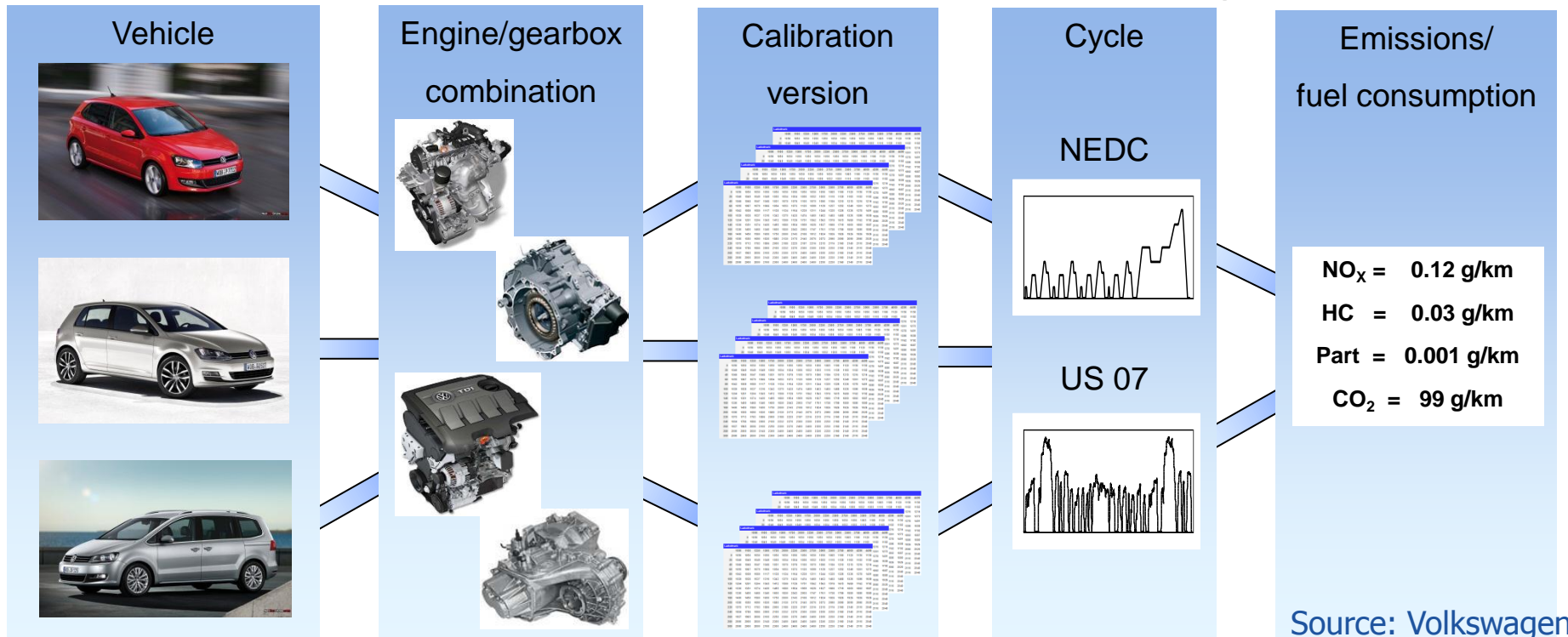
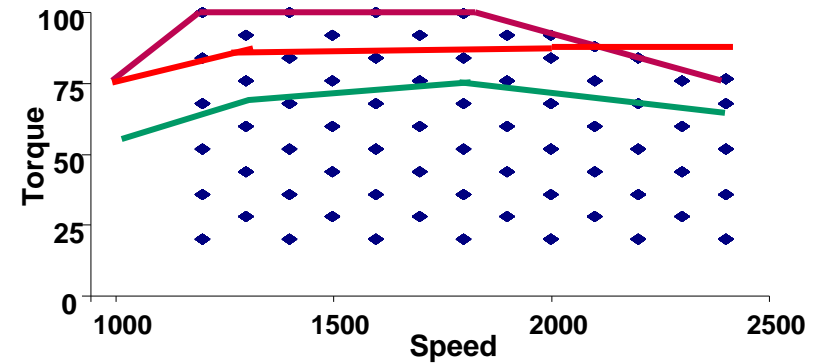
Source: Volkswagen

Broad operating region:

Vehicle types: Compact car to SUV

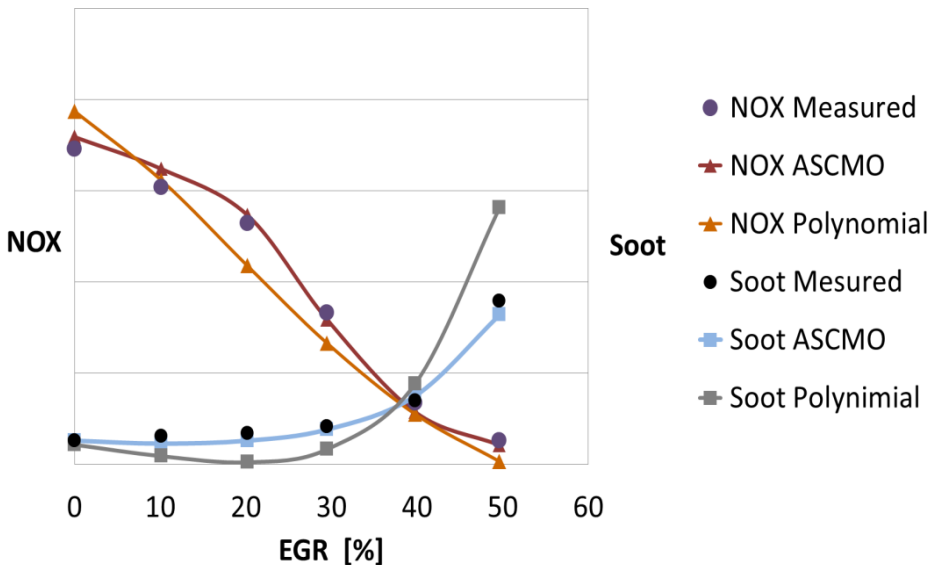
Variants: Eco / Comfort / Sport

Transmission: Manual/Automatic



Source: Volkswagen

Validation measurement: EGR-Variation



Model data set:

- 12 parameters
- Operating area: NEDC
- 600 measurement points
- Accuracy: model of fuel consumption $\leq 1\%$

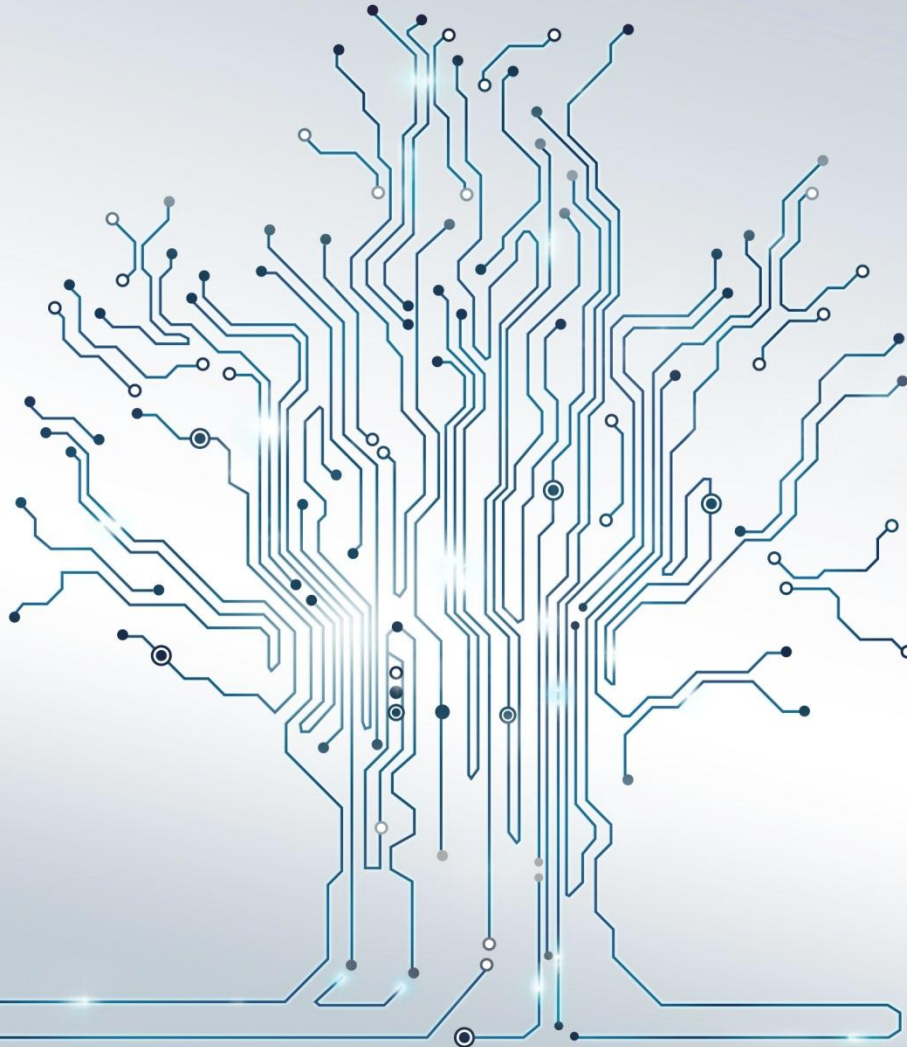
Evaluation of the model quality:

- Gaussian model: Highest quality
- Manifold opportunities to plausible the model

Results:

- By using the global engine model with ASCMO the fuel consumption could be **reduced by 2 – 4 %**
- **Reduce particulate emission** of a diesel engine by adding a post injection to an existing calibration concept **without increasing of fuel consumption.**
- Classical approach would require at least **8 weeks for the necessary 10 parameter** but with the use of ASCMO global model with **400 data points could be optimised in 1.5 days.**
- With ETAS ASCMO, application engineers are able to use **DoE independently**
- Since the launch of ETAS ASCMO, the number of **DoE users has been increasing** rapidly

Source: Volkswagen



Thank you

Muchas gracias

谢谢

Tack så mycket

Děkuji

धन्यवाद

Mille Grazie

Merci

Hvala

sağ olun

감사합니다.

有難うございました

Спасибо!

Kiitos

Д'якую

Vielen Dank

ขอบคุณ